



Balearic Islands Coastal Observing and Forecasting System





Mission Name		SOCIB_ALGBASIN_SENTINEL3 (GF-MR-0046)			
	Platform Model	Slocum 1000 G1			
Platform ID / Name / WMO Code		U184 / IDEEP00 / 68452			
Related Platforms / Missions		SDEEP00 (Parallel execution of CanalesMAY2016) SOCIB-R/V (ADCP sampling-day under SENTINEL-3) SENTINEL-3 satellite			
Start Date		2016-05-25			
End Date		2016-06-17			
Total Days	23	Total distance (Km / Nm)	601 / 325		
Survey Area (NODC or SDN region)		Algerian Basin - Mallorca-Algeria (Western Mediterranean Sea)			
Objective(s)	Hydrographic and geochemical survey of Algerian Basin (EL2 Spring-mission)				

- Validation of new along-track (L3) and gridded interpolated maps (L4) altimetry products, provided among others by the Sentinel-3 altimetry mission, in the western Mediterranean Sea by using the in-situ Glider and SOCIB-R/V available observations
- Demonstration of technical and tactical feasibility of EL2 as SOCIB's endurance line

Scientific Sensors
(name & model / serial_number / calibration date)

- CTD -SBE- / sn 0195 / 10-April-2013
- FLNTU -WetLabs- / sn2128 / 01-Feb-2011
- OPTODE -Aandera- / sn 0841 / 01-May-2013 (calibration sheets available upon request to glidertech@socib.es)

Number of Profiles

876 (CTD), 439 (FLNTU), 439 (OXY)

(majority of deep dives between 15 and 950m)

Significant **Events**

- 1st **ALG-BAS** demo-mission in 2016 (G1 deep glider)
- 2nd mission undertaken by **IDEEP00** in 2016 (powered by SAFT Lithium battpack.)
- Overlapped transects (triangular shape) South of Cabrera to begin the SENTINEL-3 1st leg on the appropriate date in order to synchronize with SOCIB-R/V transect
- May-30th: SENTINEL-3 over-passing and SOCIB-R/V simultaneous sampling. SOCIB-R/V transect completed (by IDEEP00) on June-1st
- 'silent-mode' activated in DAPP (mission not shown since
- 2 complete SENTINEL-3 swath legs covered during this mission (over Orbit #713)
- Deep-flying mode turned on during >2000m navigated waters (UTC surface strategy during the rest of it)
- Very good overall performance (no critical aborts nor errors)
- Data backup using radio link (without hull disassembly)

Mission Summary

Introduction

This mission, the 2nd one by IDEEP00 in 2016, stands for the first one in multiple senses: first SENTINEL-3 (S3) swath-sampling; first Algerian-Basin(AB) mission of the year (demo mission for an eventual AB endurance-line); first AB mission with a G1 Glider, first SOCIB-External-Access (SEA) mission and first synoptic mission with SOCIB-R/V out of Eïvissa-Channel (EC). Internal code for this mission is GF-MR-0046. Days 29 and 30 of May were under SEA and the rest was a SOCIB demo-mission

Pre-mission Report

Created prior to the start of the preparations, compiling the key preliminary aspects of this GF-MR-0043, derived from planning sessions.

Phases were executed between 11/May/2016 to 26/May/2016. All checks and configurations were undertaken according to the pre-mission-report and applicable protocols. There were neither relevant issues nor problems worth to be mentioned here. Compass error was measured in a EMIfree forest location (max. error > 20 deg so the compass needs recalibration).

Launching

This field operation (25/May) was executed by 1 ETD and 1 GF facility members on board SOCIB RIB Hurricane 9m. Glider was released in N39°11.802' E02°37.944' at 11:05-utc. The deployment was an operative and tactical success (environmental conditions were very good). Pilot was onshore. Glider executed successful test dives prior to the initial survey dive.

In general terms, it was very successful. Main preliminary objectives were all accomplished without major setbacks. The absence of critical situations resulted in no emergency actions.

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- Navigation: was very satisfactory. Fluid and continuous advancements without relevant deviations from commanded route (1,2Km in average). A single waypoint-list commanded with modifications to implement a track repetition between 28-May and 30-May and also to extend the return route to get closer to Palma's Bay. All waypoints were accomplished successfully (max. dead-reckoning error of 2,8Km). There were no interruptions due to currents nor to mission aborts. A track repetition was commanded to 'spend time' while waiting for the SOCIB-R/V(RV) sampling to occur (May-30th). Then, that day, both RV and S3 sampled synoptically with the Glider. No signs of stronger currents in the region closer to the Algerian coast. The return trip was smooth and without problems. Due to the favorable context, the Glider was commanded to approach closer to Palma's bay seeking for an easier recovery. Final traced route composed out of: (a) 2 complete legs over S3 swath-orbit #713 and (b)2 transit routes (initial and final) to move from/to release/catch sites to/from #713 leg. An average X-Y speed of 0,32m/s was accomplished (0,29m/s on diving and 0,38m/s on climbing)
- Underwater Maneuvering: was initially configured accordingly to scientific objectives, environmental conditions (mainly bathymetry for this mission) and 'flying' efficiency. (See Chart 1 for details). During the mission the strategy was changed multiple times to adapt to variations in these aspects. Basically, during the initial and final travel-routes a standard configuration (surface by UTC time, 4 times a day, infinite yo-ing, altimeter on, manual pitch control) was implemented whilst during #713 legs a deep-flying-mode was turned on (no UTC surface, surface after 2 consecutive yo's, altimeter off, manual pitch control) seeking for energetic efficiency and maximum sampling performance. Average vertical speeds of 0,15m/s (climbing) and 0,19m/s (diving) were accomplished. Both target depths (upper and bottom) remained constant during the whole mission (15 and 950 meters respectively).
- Data Logging: sampling seemed to have been successful and according to details shown in Chart 2 (89 non-critical oddities raised by science-super). The strategy remained unchanged during the whole duration of the survey and resulted in 876 CTD profiles and 439 for OXY and FLNTU each (307747m of water-column sampled with CTD and 75839m with OXY/FLNTU). Intersample mean-times for CTD, OXY and FLNTU are 2.939sec, 5.169sec and 10.056sec respectively. The number of samples taken have been: 1202292 (CTD), 748561 (OXY) and 393262 (FLNTU).

Engineering

- Power Source: Brand new Primary Lithium Battery pack with 420Ah of nominal capacity. The supply was stable and capable of fulfilling the requirements of all the on-board systems. Finally, 95,92Ah were consumed with a final reading of 98,16Ah.
- Electro-Mechanical: actuators and sensors exhibited an excellent performance (but Oddities raised by pitch-motor and digifin); Pitch control remained in 'servo-mode' during the entire survey
- Communication Systems: were very reliable and fluent. There were only 7 drop-calls and 0 missing-calls. ARGOS sent 862 messages. GPS fix time (mean) was 254 seconds and there were no pre-fix failures.
- Electronic Modules: (processors, memory cards, control boards,...) revealed no evidences of problems at all.
- Hydrodynamics: no signs of problems
- Device Error-Statistics: 0 Errors, 0 Warnings and 874 Oddities (2 ocean_pressure, 65 pitch_motor, 93 science_super (Input ringbuf overflow odds. during surface dialog), 479 digifin, 185 iridium and 50 coulomb). None of this are to be considered critical.
- o Mission Runs: the same mission run lasted the whole survey (log-file identifier 0349xxxx)

Recovery

This conclusive field operation took place as planned (17/June) in N39° 09.632' E02° 37.677', which is closer to Calanova home-port than the launching location (it was feasible to get the glider closer to coast). Glider was already at surface waiting for the recovery team (on-board SOCIB RIB Hurricane 9m, formed by 1-ETD and 1-GF) and was extracted with no problem availing a favorable sea-state. Note: a communication test was done to validate the capability of the Iridium handset to act as a 4800baud modem for a field-portable dockserver.

<u>Conclusion</u>

This phase started the same day of the recovery (17/June), which was a Friday. In order not to disassemble de hull, IDEEP00 was left downloading EBD+DBD files over the Freewave interface. By next day, Saturday, all files had been downloaded. On 21/June the conclusion resumed following the applicable protocol mainly focusing on: (1) avoiding disassembly to preserve the pressure seal; (2) external-surfaces and sensor cleaning/refurbishment (light signs of corrosion in hull side rings and almost inexistent bio-fouling growth); (3) gathered-data backup (by radio) and uploading to SOCIB's data-center for post-processing; and, finally, (4) avoiding preparation for storage and leaving in GliderLAB (enough battery capacity to undertake next Canales mission). After that, the storage status of the vehicle was "80% ready for a new preparation" (since it had not been disassembled and there was almost 200Ah available).

Administration/Notification

Although multiple administrative and notification procedures took place during the different stages described above, these have not been reported because are considered out of the scope of this report. Same applies for multimedia and public-diffusion; and also for accounting.

HHRR

Coordination amongst multiple participants (glider-techs, field-techs, scientists & open-accessusers) was fluent and efficient in spite of the field failure during recovery. There were no personal damages and the availability of each member, for all the tasks assigned at each moment, was correct (including on-alert shifts for field intervention and 24/7 glider monitoring during survey).

Detail Charts:

	Date (utc)	D_{UTI}	D_{UBI}	T_{UND}	d_{BOT}	N _{DIV}	N_{COM}	$t_{ extsf{UTC}}$	H_{WPT}
-[25/May@(M.S.)	15	950	21600	40	00	12	4,11,16,20	1000
- [31/May@08:13	15	950	14046	40	2 ⁽¹⁾	12	(disabled)	1000
- [14/Jun@12:40	15	950	21600	40	00	12	4,11,16,20	1000
- [16/Jun@15:39	15	950	21600	40	00	12	4,7 ⁽²⁾ ,11,20	1000
	17/Jun@07:00	15	65 ⁽³⁾	1800	40	2	12	4,7,11,20	1000

(1): Deep-flying mode. 2 dives at max. depth in >2000m waters of Algerian Basin
(2): Replaced next day's call (recovery day), at 16utc, to make glider call at 7utc to allow recovery strategy configuration

(3): At recovery day, 2 dives at 65m configured while waiting for recovery team

(M.S.): Mission Start

D_{UTI}: Underwater Top Inflection Depth (m) D_{UBI}: Underwater Bottom Inflection Depth (m)

T_{UND}: Average Period of Underwater Navigation (secs)

d_{BOT}: Minimum Distance to Sea-floor to be kept (m)

 N_{DIV} : Surface upon completion of this # of dives

 N_{COM} : Surface if this amount of hours without stable communications (hrs)

 t_{UTC} : Surface at this particular UTC times

H_{WPT}: Surface if a waypoint is hit within that distance (m)

Chart 1 Summary of Underwater Strategies (Navigation)

Date (utc)	S_{EN}	$f_{\sf SMP}$	D_{RNG}	M_{DIV}	M _{CLI}
	CTD	0,5000	[-5, 2000]	yes	yes
25/May/2016	OXY	0,2500	[-5, 2000]	yes	no
(at Mission Start)	FLNTU	0,1250	[-5, 150]	yes	no
	FLNTU	0,0625	[150, 300]	yes	no

S_{EN}: Sensor type

 f_{SMP} : Frequency of sampling (Hz)

D_{RNG}: Depth range this configuration applies (m) M_{DIV} : Sampling during Diving maneuver M_{CLI}: Sampling during Climbing maneuver

Chart 2 Summary of Commanded Sampling Strategies

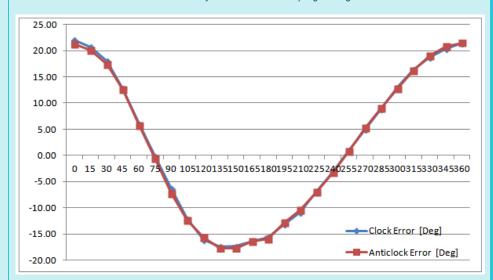
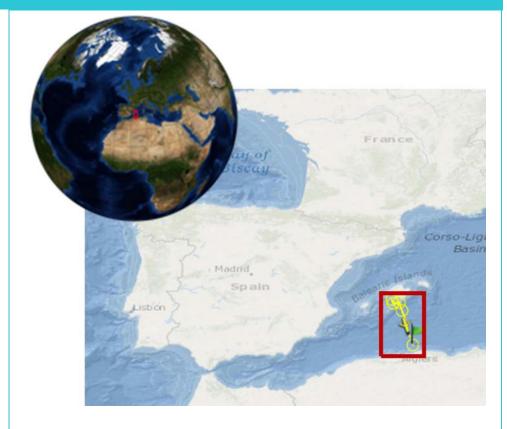


Fig 3.1- Error measured during Compass Error Check procedure in an electromagnetic-field-free environment located in a forest close to IMEDEA (in Esporles)

Principal Investigator (e-mail or contact phone/address)	 Prof. Joaquim Tintoré jtintore@socib.es (+34 971439821) Dr. Ananda Pascual apascual@imedea.uib-csic.es (+34 971611732)
Institute	SOCIB in collaboration with IMEDEA
Project Affiliation (web-site)	http://www.socib.eu
Partnership / Participation	• SOCIB • IMEDEA
Glider Software Version	Nav : v7.13 Acomms, Payload: 3.17
Data Retrieval (real-time [RT] / delayed-mode [DM])	 RT: sub-set via satellite link during the first part of the mission. Engineering data only afterwards. DM: wireless download via radio link to not disassemble the glider
Compass Calibration (specify procedure)	Compass error was measured. Observed error followed a well-known sinusoid-shape although the glider followed traced-route very well(See Figure 3.1)
Battery Type	SAFT Custom Lithium Pack (430Ah-nominal capacity) (With in-house-designed ballasting chassis)
Battery Consumption (Ah)	97.157Ah (reading from 1.539 to 98.697Ah)
Data Available From	http://thredds.socib.es/thredds/fileServer/auv/glider/ideep00- ime_sldeep000/L2/2016/dep0017_ideep00_ime-sldeep000_L2_2016- 05-25 data dt.nc
Further Details	glidertech@socib.es

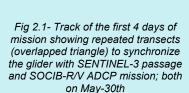
(Map providing general overview of Survey Area)



On-line Track http://apps.socib.es/dapp/?deployments=621-9-0-FFFF00&layers=isobaths,ocean_basemap&units=scientific

Figure 2

(Map providing detailed overview of Survey Area and traced Flight Path with surface points if possible)



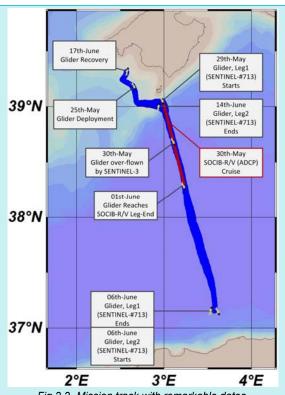
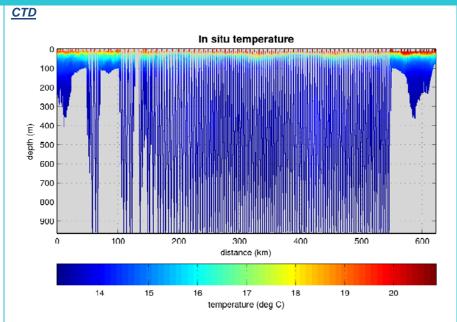


Fig 2.2- Mission track with remarkable dates

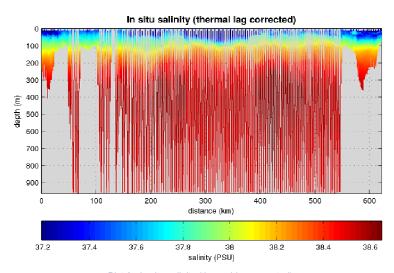
Scientific Preliminary Review

(Compilation of preliminary postprocessing plots provided by SOCIB's datacenter glidertoolbox and processing services. Contact data.center@socib.es for further info. Plots available through DAPP -See Figure 1 -. Comments provided by SOCIB's scientific staff)

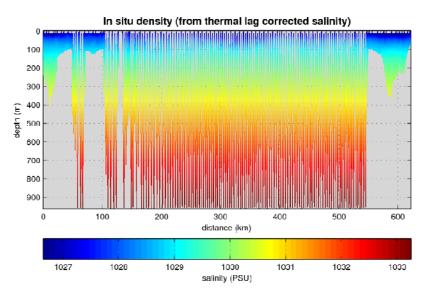


Plot 1 – In situ temperature (TOP: full depth range, BOTTOM: first 200m)

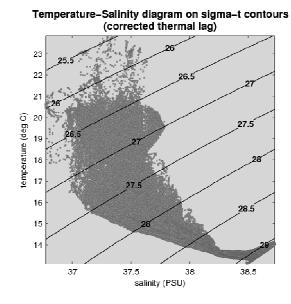
The temperature plot shows a subsurface low temperature feature in the LIW layer (300 – 600 m+), which can be more clearly seen in the potential temperature plot or in the salinity plot following this one. The thermocline is between 30 – 50 m. In there is a subsurface high salinity feature, which could represent an eddy core (at 200 km)). In addition on the return transect in the LIW layer there is a high salinity feature extending, from 200 m to 800+ m and some 10 km in width at 420 km, this could be a sub mesoscale vortex, for example as described by Bosse et al 2015, adjacent to the larger eddy feature. The signature of the Algerian current, with lower salinities in the surface to 100 m is visible in the southern part of the transect (the center in the plot, around 320 km).



Plot 2- In situ salinity (thermal-lag corrected)



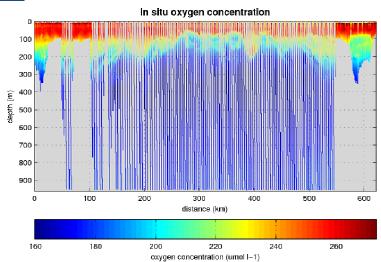
 ${\it Plot~3-density~derived~from~corrected~salinity~(thermal-lag~correction)~and~temperature}$



Plot 4 – T-S diagram (thermal-lag corrected)

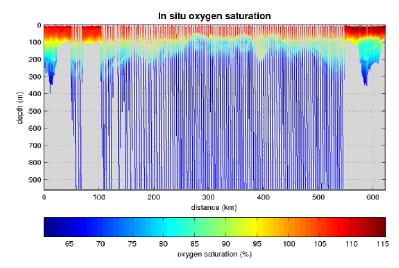
In the T-S diagram we can see the feature observed in plot 1 and plot 2, there is a high salinity water mass in the range of the LIW (S > 38.35 with θ > 13.0). Also we can see Atlantic fresh waters coming from the Algerian current corresponding to salinities lower than 37.5. Also MAW (Modified Atlantic Water) is observed with salinities 37.5 – 38.35. There is no evidence WIW or WMDW, however this is to be expected given the location of the transect and the depth to which the glider samples.

OXYGEN



Plot 7 – in situ oxygen concentration

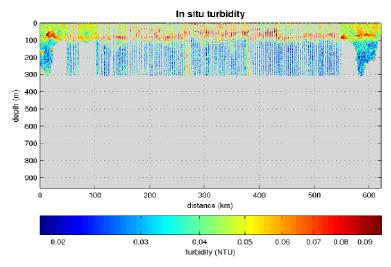
There are some interesting changes in the oxygen across the 2 transects, with higher concentrations in the surface out of the Algerian current around 320 km and a blob of higher oxygen concentration between 100 and 200 m around 400 km perhaps associated with the possible sub surface vortex feature.



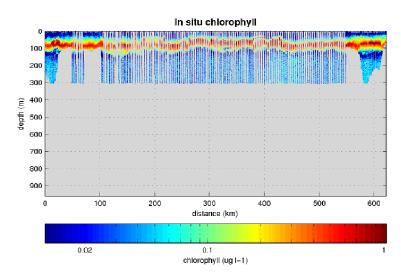
Plot 8 – in situ oxygen saturation

TURBIDITY & CHLOROPHYLL

The levels of turbidity seems to be constant across both transects with a rising of turbidity in the surface layer associated with the Algerian Current (center of the plot). The level of chlorophyll remains constant over the two transects with a sub surface maxima below the thermocline at approximately 80 m. The turbidity sub surface maximum appears to be approximately coincident with the chlorophyll maxima.



Plot 9 – in situ turbidity



Plot 10 - in situ fluorescence

Bosse A., P. Testor, L. Mortier, L. Prieur, V. Taillandier, F. d'Ortenzio and L. Coppola (2015a): Spreading of Levantine Intermediate Waters by Submesoscale Coherent Vortices in the Northwestern Mediterranean Sea as observed with gliders, JGR, DOI: 10.1002/2014JC010263