

## Glider Mission Summary Report

2012 - 2015 SOCIB (CSIC)

ALBOREX-PERSEUS-2014 (gf-mr-0027)



Balearic Islands Coastal Observing and Forecasting System









Mission Name	ALBOREX-PERSEUS-2014 (gf-mr-0027)
Platform Model	Slocum 1000m G1
Platform ID / Name / WMO Code	U184 / IDEEP00 / (n/a)
Related Platforms / Missions	ICOAST00 / ALBOREX(Perseus) & FRIPP (Jerico-tna)
Start Date	2014-05-25
End Date	2014-05-30
Total Days 6	Total distance (Km / Nm) 127,0 / 69,0
Survey Area (NODC or SDN region)	Alboran Sea (Western Med.)
Objective(s)	(Within Subtask 3.3.4 of PERSEUS) to design and conduct a multi- platform synoptic experiment (ALBOREX) in the eastern Alboran Sea, an area characterized by sharp gradients that lead to the appearance of intense mesoscale and submesoscale features The final goal is to monitor and establish the vertical exchanges associated with mesoscale and submesoscale and their contribution to upper ocean interior exchanges.
Scientific Sensors (name & model / serial_number / calibration date)	CTD A4468-S.B.E / sn 0195 / 10-Apr-2013 FLNTUSLK -WetLabs- / sn2128 / 01-Feb-2011 OPTODE_3830 -Aandera- / sn 0841 / 14-Sep-2010
Number of Profiles	136 (CTD), 136 (FLNTU), 136 (OXY) (all of these profiles at max. depth range: 0 to 500 m)
Significant Events	Poor comms. during launching Payload error during the first night which prevented from taking samples during 8 hours Strong currents Pressure-sensor oddities Mission interrupted due to GPS acquiring improper fixes
Mission Summary	IDEEP00 underwent through long enough preparation and water-testing to be loaded on-board R/V-SOCIB considered to be in optimal conditions.  The launching, at N37° 09.141′ W00° 41.630′, from R/V-SOCIB, was entirely commanded from IMEDEA and was conditioned by poor Iridium communications that caused the whole mission-start operation to be longer than expected.  During the execution phase, mechanical systems operated as expected. On the contrary, there were significant issues with the sensor Payload (turned off during the first night) and GPS (mission stop due to fixes not being updated properly). Additionally, a second mission abort occurred due to a spurious behavior error. In spite of all that, the execution was, in general terms, successful and adjusted to the plans. With respect to the traced route, IDEEP00 was seriously pushed by currents which forced pilots to modify the commanded route a few times and resulted in an overall different track than initially planned.  The recovery was performed using the RIB boat of R/V-SOCIB, at N36° 48.113 W00° 16.084′, during a quick and perfectly executed action.  After that, mission conclusion was carried out and data uploaded to SOCIB's FTP servers.

www.socib.es

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Institute	
Project Affiliation (web-site	
Partnership / Participation	PERSEUS-ALBOREX-Plan: CSIC(ES), SOCIB(ES), OGS(IT), IEO(ES), CNR(IT), SASEMAR(ES), WHOI(USA), UCLA(USA), UMA(ES)
Glider Software Version	v7.13 (navigation), v3.17 (science)
<b>Data Retrieva</b> (real-time [ RT ] / delayed-mode [ DM	
Compass Calibration (specify procedu	0040) 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Battery Type	Manufacturer's original Alkaline batt.pack (145Ah-nominal cap.)
Battery Consumption (Ah	
Data Available Fron	
Full Mission Report Fron	
Technical Contac	
Figure 1  (Map providing general overview of Survey Area)	SPAIN
Mission Summary  (Map providing detailed overview of Survey Area and traced Flight Path with surface points if possible)	cartagena • ALGERIA