

# Glider Mission Summary Report

CANALES CAMPAIGN 2019

SOCIB GLIDING SEP2019 (GF-MR-0097)



Balearic Islands  
Coastal Observing  
and Forecasting  
System



Govern de les Illes Balears

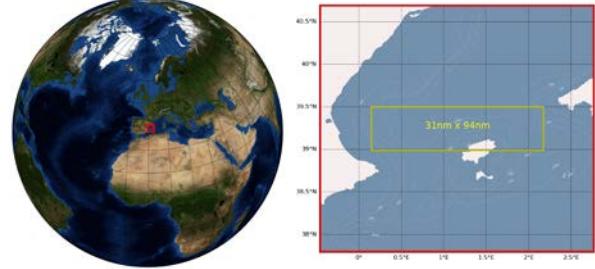


<b>Mission Name</b>	SOCIB_ENL_CANALES_SEP2019_SDEEP01_GFMR0097
<b>Platform Model</b>	<i>Slocum 1000m G2</i>
<b>Platform ID / Name / WMO Code</b>	<i>U244 / SDEEP01 / 68967</i>
<b>Related Platforms / Missions</b>	<i>None</i>
<b>Glider Software Version</b>	<i>Nav : 8.2 Acomms, Payload: 8.2</i>
<b>Start Date (UTC)</b>	<i>2019-09-17 09:08:26</i>
<b>End Date (UTC)</b>	<i>2019-10-29 07:55:12</i>
<b>Total Days</b>	<i>41.9</i>
<b>Total distance (Km / Nm)</b>	<i>822.16[km] 443.93[nm]</i>
<b>Battery Consumption (Ah)</b>	<i>231.661 (reading from 188.316 to 419.977)</i>
<b>Survey Area</b>	<i>Mallorca and Eivissa Channels (Western Mediterranean Sea)</i>
<b>Objective(s)</b>	<ul style="list-style-type: none"> <li><i>Establishing the variability of the N/S exchange of water masses that occur through the Ibiza Channel(IC). Sampling standard transects across the Ibiza Channel several times using physical and biogeochemical sensors. No greater than 1 month gap in between consecutive iterations. The Mallorca Channel is also sampled when operationally practical.</i></li> </ul>
<b>Significant events</b>	<ul style="list-style-type: none"> <li><i>This mission was the successful one after 2 tries:</i> <ul style="list-style-type: none"> <li><i>First one was GFMR0095 failed due to a bug on software version 8.3</i></li> <li><i>Second one malfunction on the altimeter, GFMR0096</i></li> </ul> </li> <li><i>By the end of the mission a malfunction on CTD pump was detect, it occurred during the entire mission</i></li> <li><i>This glider was prepared with Teledyne, B.Allsup</i></li> <li><i>This glider was prepared just after a refurbishment</i></li> </ul>

Mission Preparation	<ul style="list-style-type: none"> <li><i>Preparation was a typical one, most of the steps belong to GFMR0095.</i></li> <li><i>This preparation was done under the supervision of B.Allsup (TWR) in order to update and improve SOCIB protocols.</i></li> </ul> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left; padding: 2px;"><b>Step</b></th><th style="text-align: left; padding: 2px;"><b>Status</b></th><th colspan="2" style="padding: 2px;"><b>Comments</b></th></tr> </thead> <tbody> <tr> <td style="padding: 2px;">Hardware check</td><td style="padding: 2px;">Ok</td><td colspan="2"></td></tr> <tr> <td style="padding: 2px;">Comms check</td><td style="padding: 2px;">Ok</td><td colspan="2" style="padding: 2px;">Avoided. SMS service out of order</td></tr> <tr> <td style="padding: 2px;">Batteries check</td><td style="padding: 2px;">Ok</td><td colspan="2" style="padding: 2px;">TWR battery pack</td></tr> <tr> <td style="padding: 2px;">Ballasting check</td><td style="padding: 2px;">Ok</td><td style="padding: 2px;">Target density: 1025,613 g/L</td><td style="padding: 2px;">Tank density: 1026,326 g/L</td></tr> <tr> <td style="padding: 2px;">Final sealing check</td><td style="padding: 2px;">Ok</td><td colspan="2"></td></tr> <tr> <td style="padding: 2px;">Fileset check</td><td style="padding: 2px;">Ok</td><td colspan="2"></td></tr> <tr> <td style="padding: 2px;">Harbor check</td><td style="padding: 2px;">Ok</td><td colspan="2"></td></tr> <tr> <td style="padding: 2px;">Compass Error Measurement</td><td style="padding: 2px;">NA</td><td colspan="2"></td></tr> </tbody> </table>			<b>Step</b>	<b>Status</b>	<b>Comments</b>		Hardware check	Ok			Comms check	Ok	Avoided. SMS service out of order		Batteries check	Ok	TWR battery pack		Ballasting check	Ok	Target density: 1025,613 g/L	Tank density: 1026,326 g/L	Final sealing check	Ok			Fileset check	Ok			Harbor check	Ok			Compass Error Measurement	NA		
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<i>Deployment</i>	<p>This deployment was concatenated from GFMR0096, just after changing the altimeter.</p> <table border="1"> <tr> <td>Vessel:</td><td>SOCIB I</td></tr> <tr> <td>Personnel:</td><td>1 ETD + 1 GF</td></tr> <tr> <td>Location:</td><td>Dragonera N 39°24.6920' E 02°18.1146'</td></tr> </table>	Vessel:	SOCIB I	Personnel:	1 ETD + 1 GF	Location:	Dragonera N 39°24.6920' E 02°18.1146'																		
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<i>Navigation</i>	<p>It was satisfactory during most mission time. The glider responded well to the commanded target waypoints.</p> <p>Figure 1 – Commanded Waypoints</p>																								
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<i>Engineering</i>	<table border="1"> <thead> <tr> <th>Sensor</th> <th>Oddities</th> <th>Warning</th> <th>Errors</th> </tr> </thead> <tbody> <tr> <td>GPS</td> <td>5</td> <td>1</td> <td>0</td> </tr> <tr> <td>pitch_motor</td> <td>6</td> <td>0</td> <td>0</td> </tr> <tr> <td>science_super</td> <td>45</td> <td>0</td> <td>0</td> </tr> <tr> <td>digifin</td> <td>880</td> <td>5</td> <td>0</td> </tr> <tr> <td>IRIDIUM</td> <td>160</td> <td>0</td> <td>0</td> </tr> </tbody> </table> <p>Figure 2 – Errors, warnings and oddities</p>	Sensor	Oddities	Warning	Errors	GPS	5	1	0	pitch_motor	6	0	0	science_super	45	0	0	digifin	880	5	0	IRIDIUM	160	0	0
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<i>Communication Systems</i>	<p>Total number iridium calls [num]: 146.0      Iridium calls to secondary [num]: 1      ON overall iridium period [s]: 17192      Iridium calls state from 99 to 10 [num]: 152      Iridium calls state from 0 to 99 [num]: 9      Iridium calls state from 2 to 99 [num]: 141      Iridium calls state from 4 to 99 [num]: 1      Iridium calls state from 2 to 99 with c_iridium_on = 1 (Drop calls) [num]: 2</p>																								
<i>Contextual/Awareness Sensors</i>	<p>Pressure transducer, internal vacuum and internal temperature worked correctly.      Compass also reported coherent values.      Altimeter detected the bottom correctly.</p>																								

	Hull/Hydrodynamics	No signs of problems																																																																																																																																																																																		
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<b>Principal Investigator</b> (e-mail or contact phone/address)	<ul style="list-style-type: none"> <li>Prof. Joaquim Tintoré <a href="mailto:jtintore@socib.es">jtintore@socib.es</a> (+34 971439821)</li> </ul>
<b>Institute</b>	<ul style="list-style-type: none"> <li>SOCIB</li> </ul>
<b>Project Affiliation</b> (web-site)	<a href="http://www.socib.eu">http://www.socib.eu</a>
<b>Partnership / Participation</b>	<ul style="list-style-type: none"> <li>IMEDEA(CSIC-UIB)</li> </ul>
<b>Data Retrieval</b> (real-time [ RT ] / delayed-mode [ DM ])	<ul style="list-style-type: none"> <li>RT: sub-set via satellite link at each surface maneuver</li> <li>DM: full/direct memory card backup after glider disassembly during Conclusion mission-phase</li> </ul>
<b>Data Available From</b>	<a href="http://thredds.socib.es/thredds/catalog/auv/glider/sdeep01-scb_sdeep001/catalog.html">http://thredds.socib.es/thredds/catalog/auv/glider/sdeep01-scb_sdeep001/catalog.html</a>
<b>Further Details</b>	<a href="mailto:glidertech@socib.es">glidertech@socib.es</a>
<b>Global Overview</b>	 <p>Figure 3 - Map providing general overview of the Survey Area</p> <p>Online track: <a href="http://apps.socib.es/dapp/?deployments=983-43-100-FF66CC&amp;layers=none&amp;units=scientific">http://apps.socib.es/dapp/?deployments=983-43-100-FF66CC&amp;layers=none&amp;units=scientific</a></p>

## Scientific Preliminary Review

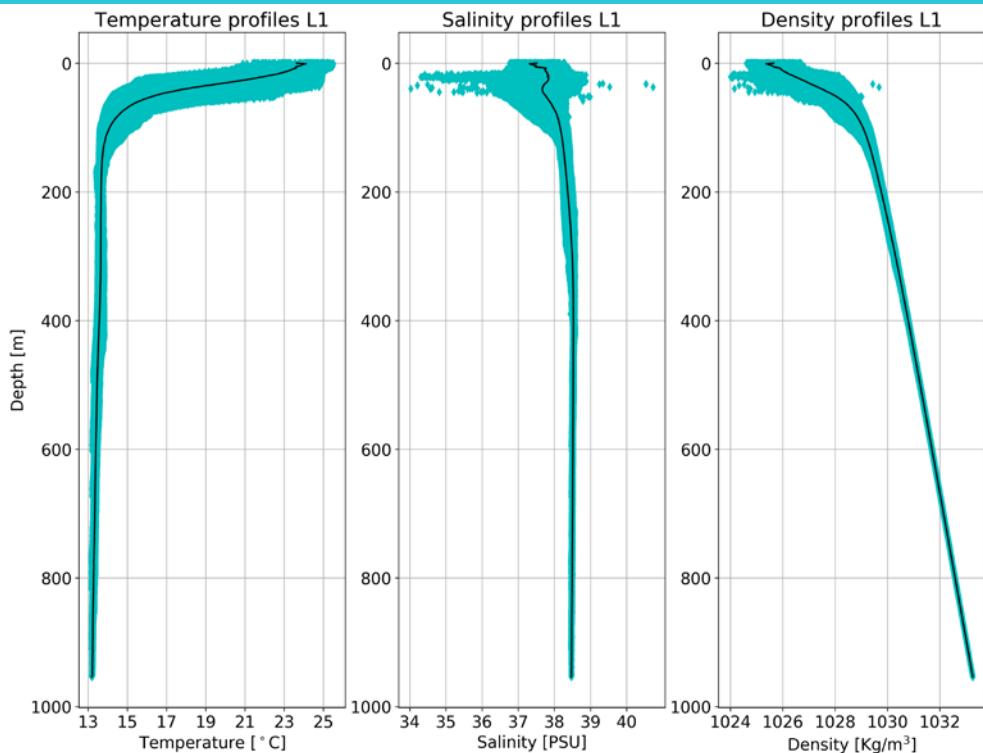


Figure 4 - CTD profiles

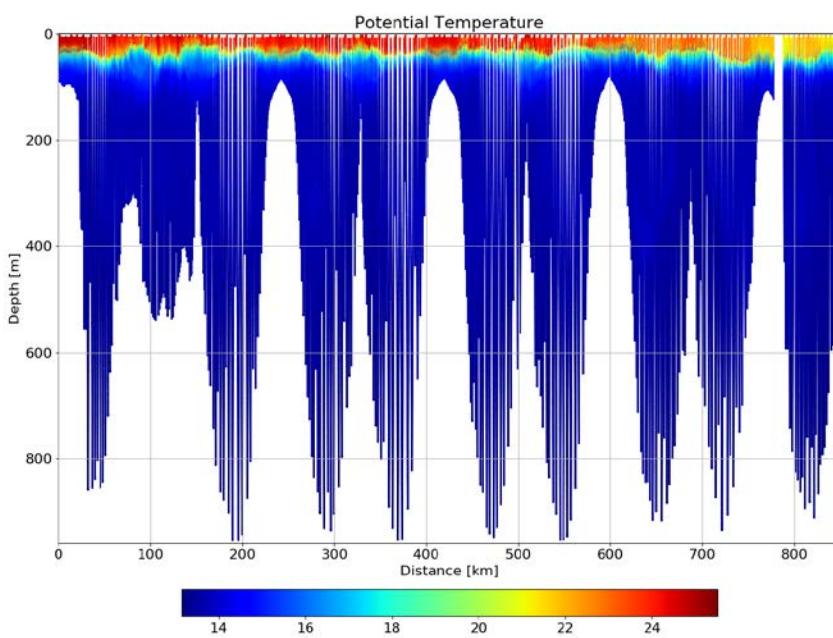


Figure 5 - Potential temperature (full depth range)

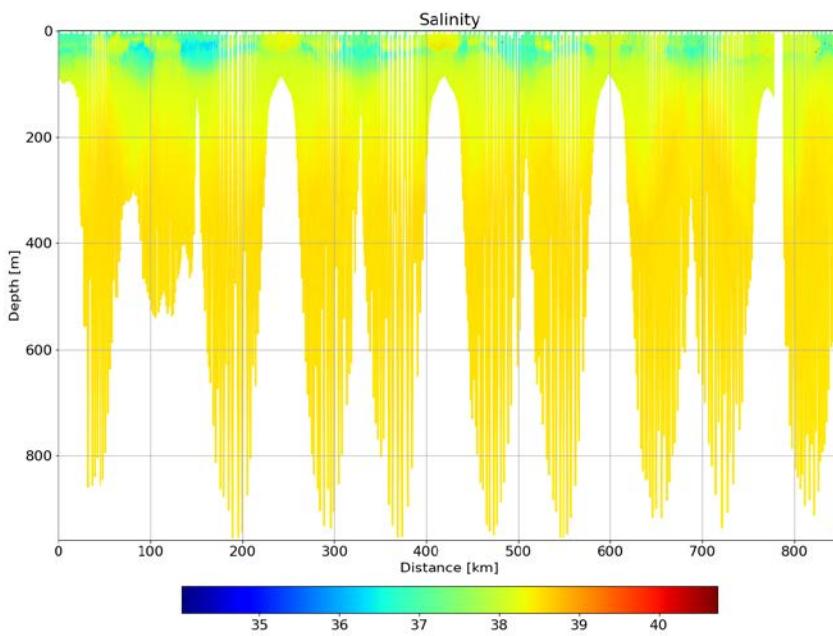


Figure 6 - Corrected salinity (full depth range)

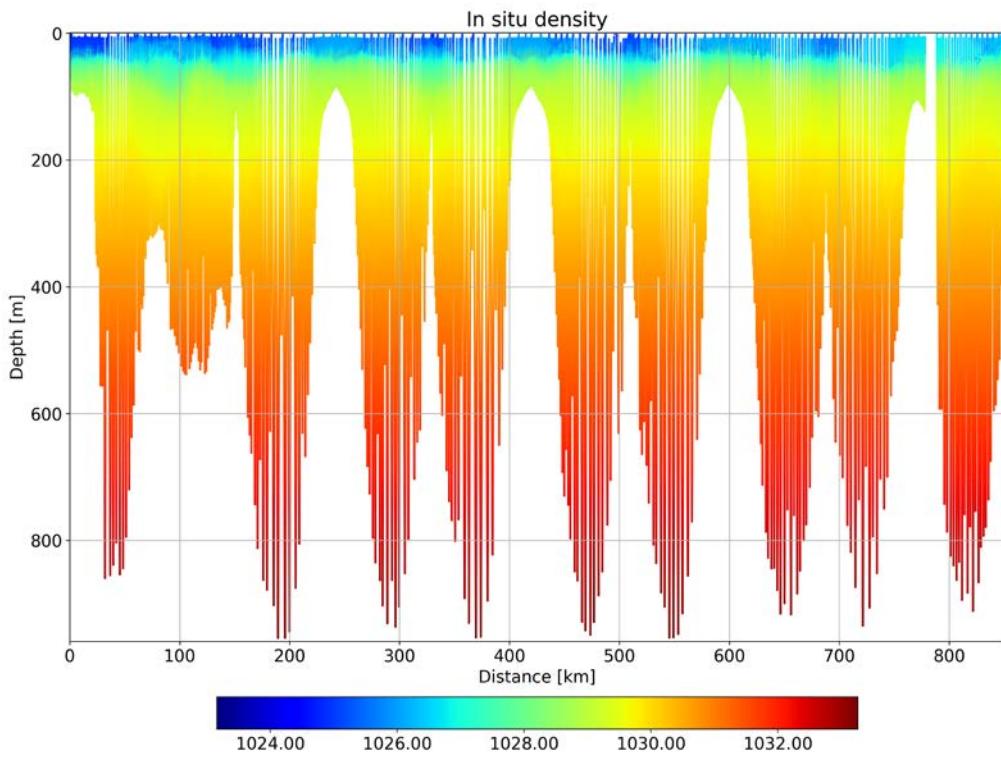


Figure 7 – In-situ Density derived from corrected salinity and temperature (full depth range)

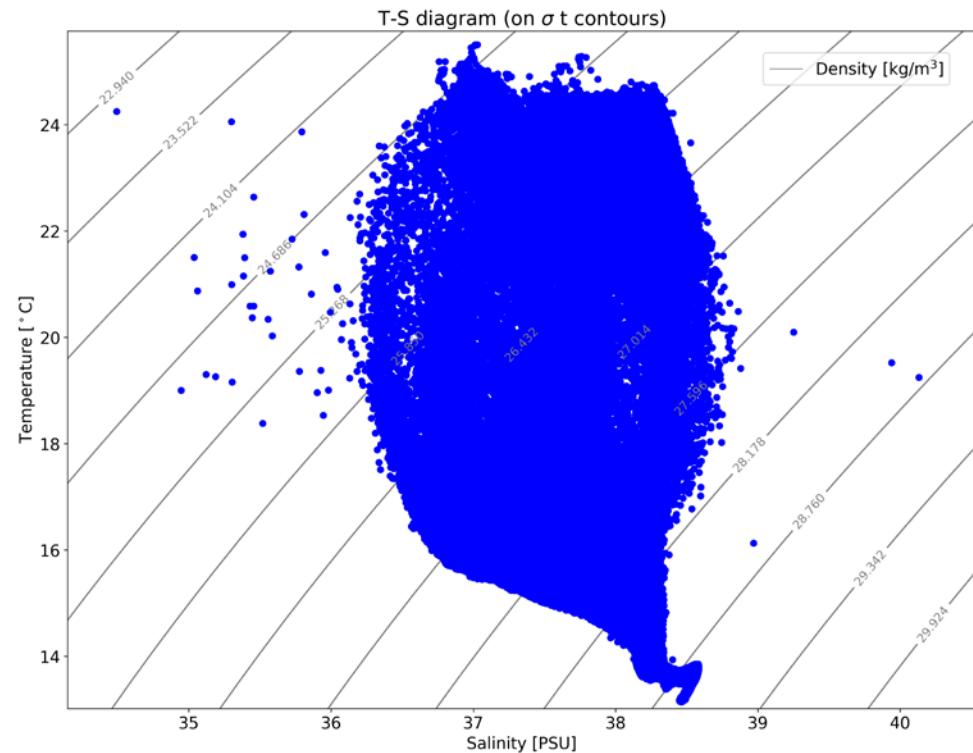


Figure 8 - T-S diagram (thermal-lag corrected)

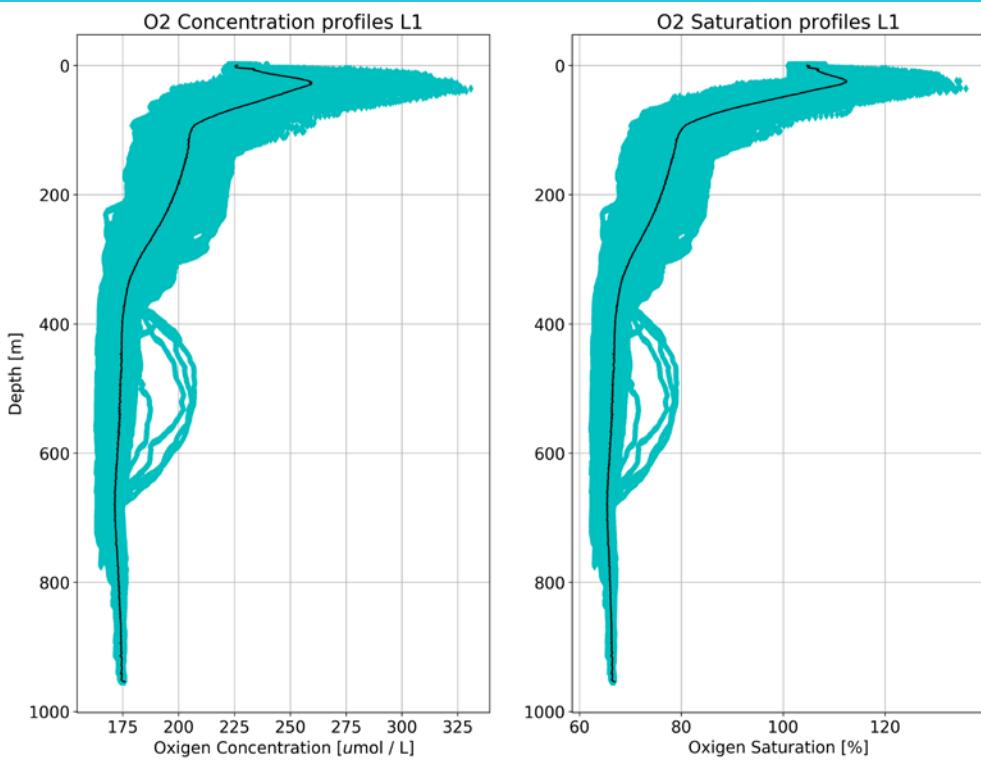


Figure 9 - In-situ oxygen profiles

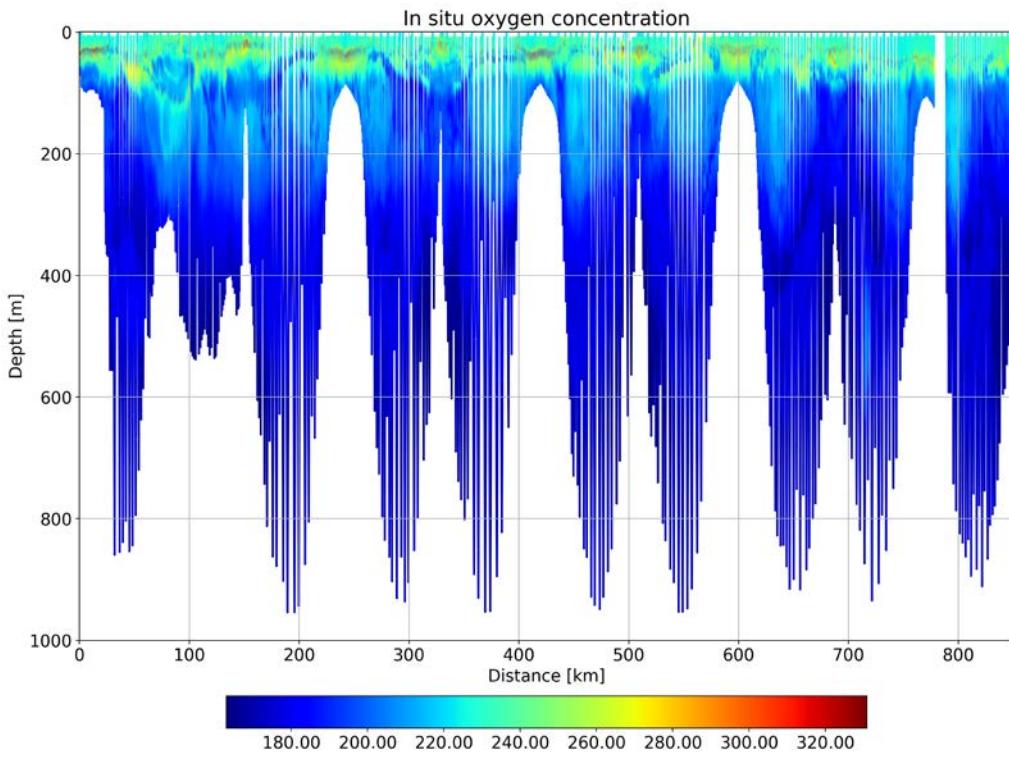


Figure 10 - In-situ oxygen concentration

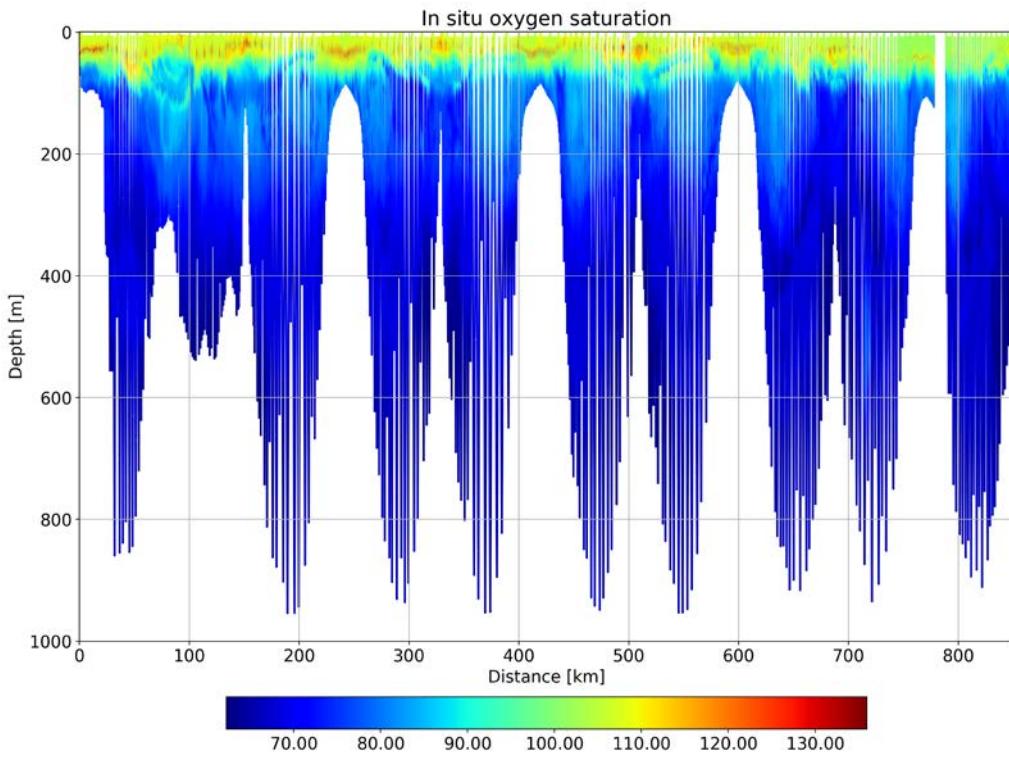


Figure 11 - In-situ oxygen saturation

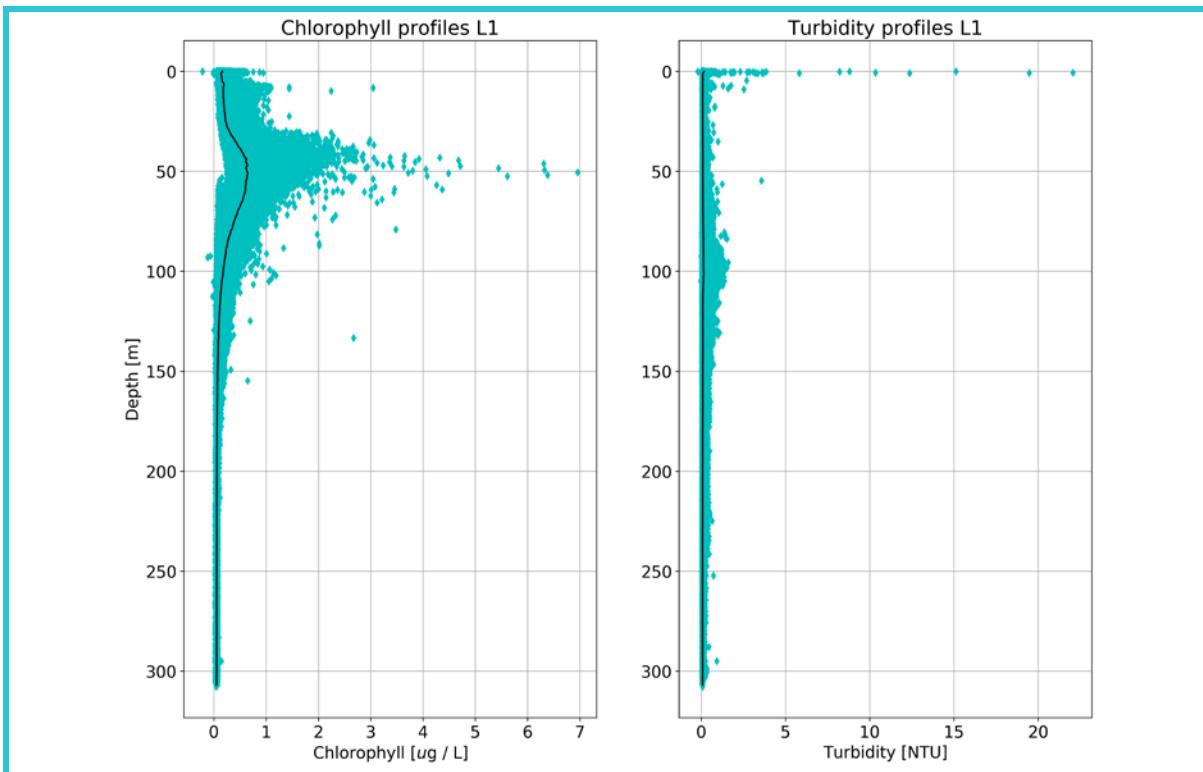


Figure 12 – In situ Chlorophyll and Turbidity profiles

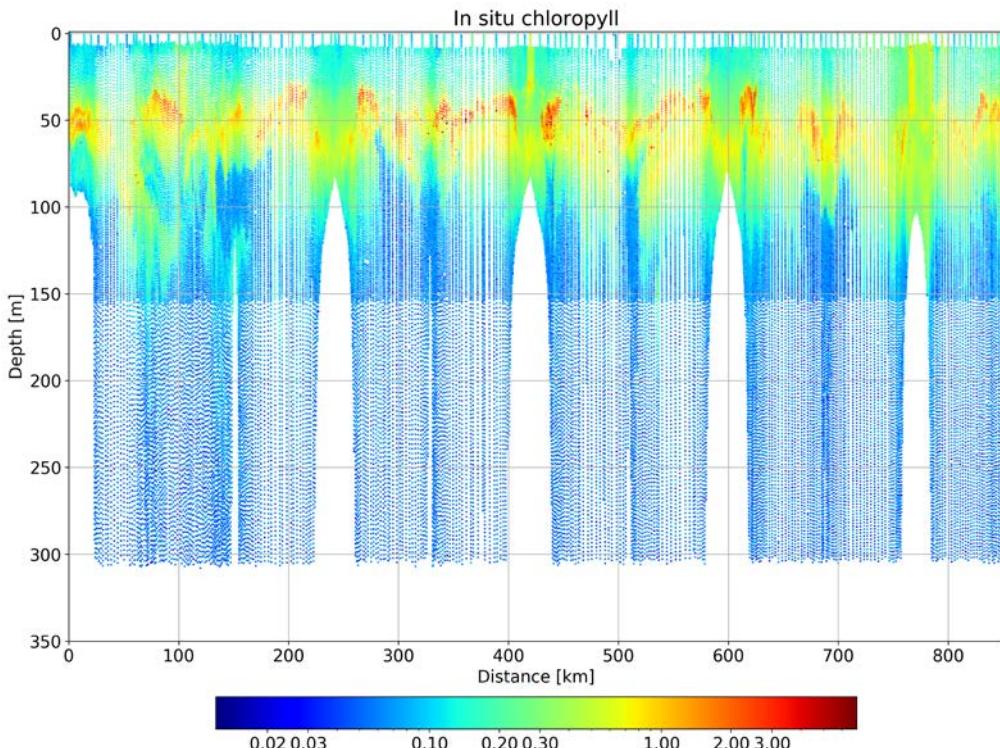


Figure 13 – In situ Chlorophyll

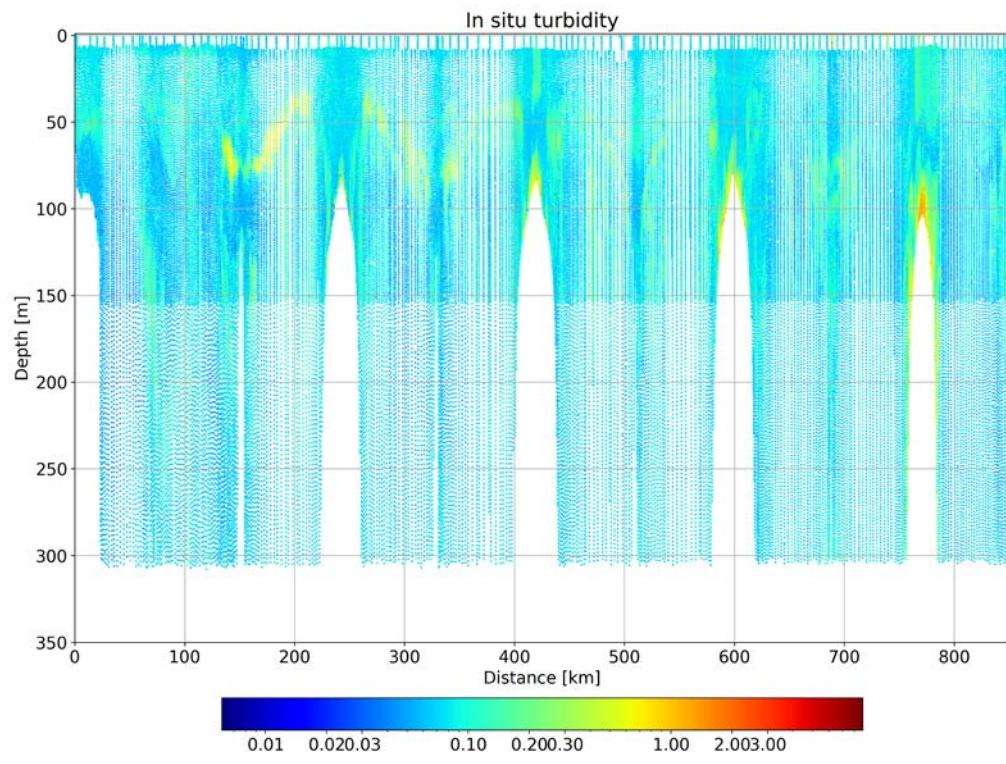


Figure 14 – In situ Turbidity

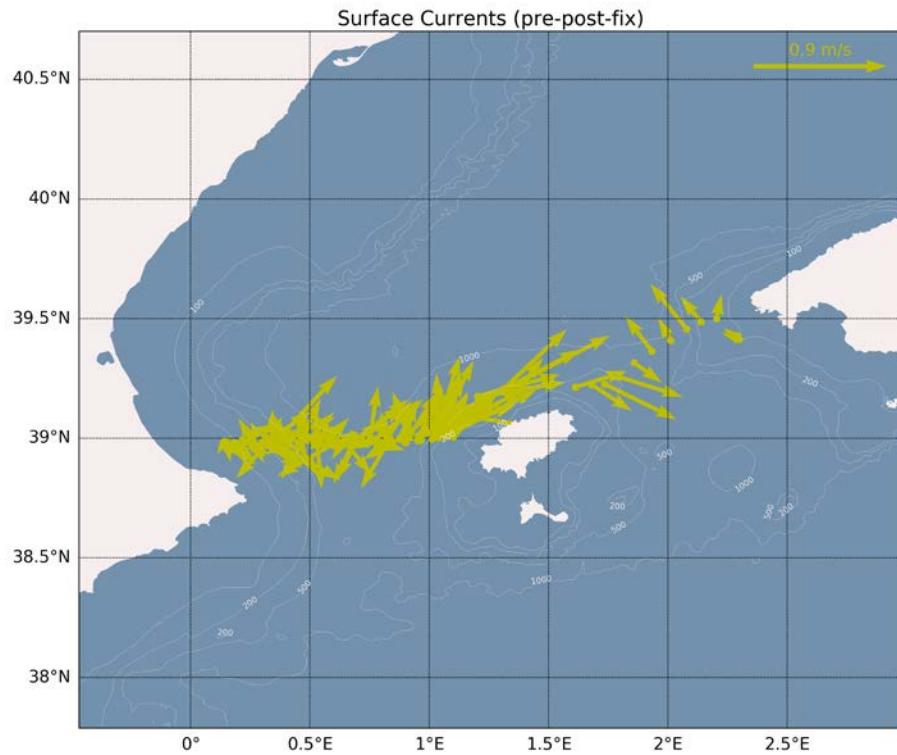


Figure 15 – Surface currents based on pre and post fix